

APPENDIX A
"CLEAN" VERSION OF EACH PARAGRAPH/SECTION/CLAIM
37 C.F.R. § 1.121(b)(ii) AND (c)(i)

CLAIMS (with indication of amended or new):

(Amended) 26. Apparatus of claim 24, wherein the means for adjusting and mechanically storing contain means for manually adjusting the elements with respect to different cutting depths.

AI (Amended) 27. Apparatus of claim 24, wherein the means for adjusting and mechanically storing contain a remote controllable drive for adjusting said elements.

(Amended) 28. Apparatus of claim 24, further containing a housing having wall means defining an enclosed space.

(Amended) 30. Apparatus of claim 29, wherein said wall means include an upper wall wherein said opening is located for downward manual access to said enclosed space.

(Amended) 31. Apparatus of any one of claims 24-30, wherein said individual elements are shafts having respective, parallel longitudinal axes spaced from and at least approximately parallel to a central axis, said individual elements being movable to said respective positions in directions parallel to said longitudinal axes.

(Amended) 32. Apparatus of any one of claims 24-30, wherein said individual elements contain at least two stop surfaces or an unlimited number of stop surfaces defined by a curve (cam control device).

(Amended) 33. Apparatus of any one of claims 24-30, wherein said individual elements contain a wedge, especially a wedge with a stair like stop surface.

(Amended) 34. Apparatus of any one of claims 24-30, wherein said individual elements contain a plurality of alternatively selectable or unselectable, fix positioned stop elements for controlling the cutting depth, whereby the cutting means have co-operators for co-operation with said stop elements to limit and control the cutting depth.

A3 (Amended) 36. Apparatus of any one of claims 24-30, wherein said individual elements contain at least one position sensor for detecting the actual position axial and/or radial position of the cutting means in relation to the axis of a cable.

A4 (Amended) 39. Apparatus of claim 24, wherein at least one element is positionable by a motor, by pneumatic or by an electromagnet.

A5 (Amended) 42. Apparatus of claim 40 or 41, wherein the storage or the storing elements may be remote controlled by a mechanical or electrical remote control or a drive remote control.

(Amended) 43. Apparatus of claim 40 or 41, wherein the storage or the storing elements contain a scale or readout for adjusting and/or displaying the stored values.

A6 09787326-060501 (Amended) 47. Apparatus of claim 1, wherein at least the depth information storage and any connected system is adapted to - at least relatively - measure the cutting depths on a gauge or on a prestripped cable functioning as a gauge.

A7 (Amended) 49. Apparatus of claim 1, wherein at least in one of the drives the torque or power consumption is measured - preferably wherein the power consumption is measured to calculate the torque output - and wherein a signal consumption is measured to calculate the torque output - and wherein a signal representative for said torque is displayed on a readout or sent to an interface or used to control said at least one drive.

A8 (Amended) 51. Cable stripping apparatus with a cable clamping mechanism containing a clamp with the possibility to control the clamping pressure, especially according to claim 1, characterized in that the clamp is subsequently controllable by two control members, wherein said control members are interconnected by a spring element and wherein one of said control members is directly driven by a control drive, and wherein said second of said control members is driven via said spring element from said first of said control elements.

A9 (Amended) 53. Apparatus of claim 1, wherein all storing elements are mechanical.

(Amended) 62. Apparatus of any one of the claims 56-61, wherein said apparatus includes an electronic storage for electronically storing a plurality of values corresponding to respective lengths from said terminal end to each of said cuts.

(Amended) 63. Wire processing apparatus according to claim 1, containing:

- A10
- a) frame;
 - b) wire gripper mounted upon said frame;
 - c) motor actuable to move said gripper between a fixed first position, spaced from said wire and a variable second position, forcibly engaging and fixing the position of said wire;
 - d) an indexer for indexing said motor a number of steps defining the distance of movement of said gripper from said first to said second position; and
 - e) selector for selectively varying said number of steps, thereby varying said distance of movement from said first to said second position and the force exerted by said gripper on said wire in said second position of said gripper.

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